

One-Matrix functional theory

$$\gamma(r, r') = N \int dr_2 \dots dr_N \Psi_0^*(r, r_2, \dots, r_N) \Psi_0(r', r_2, \dots, r_N)$$

$$E_v[\gamma] = T[\gamma] + \int dr dr' v(r, r') \gamma(r', r) + E_{int}[\gamma]$$

Is there a Kohn-Sham system?

$$\gamma(r, r') = \sum_j^{\text{occ}} \phi_j(r) \phi_j^*(r')$$

$$\gamma(r, r') = \sum_j f_j \phi_j(r) \phi_j^*(r')$$

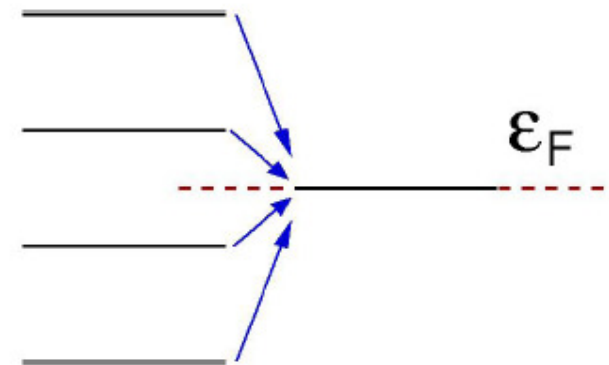
$$\begin{aligned} \hat{h} &= \frac{\delta E_v}{\delta \gamma} \\ &= -\frac{1}{2m} \nabla^2 + \int dr' v_s(r, r') \end{aligned}$$

$$v_s(r, r') = v(r, r') + \frac{E_{int}}{\delta \gamma(r', r)}$$

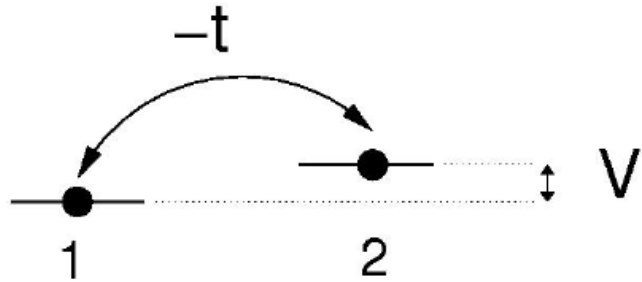
$$\frac{\partial E_v}{\partial f_j} = \epsilon_F$$

$$\Rightarrow \hat{h} \rightarrow \epsilon_F \hat{1}$$

Total degeneracy



Example: 2-site Hubbard model



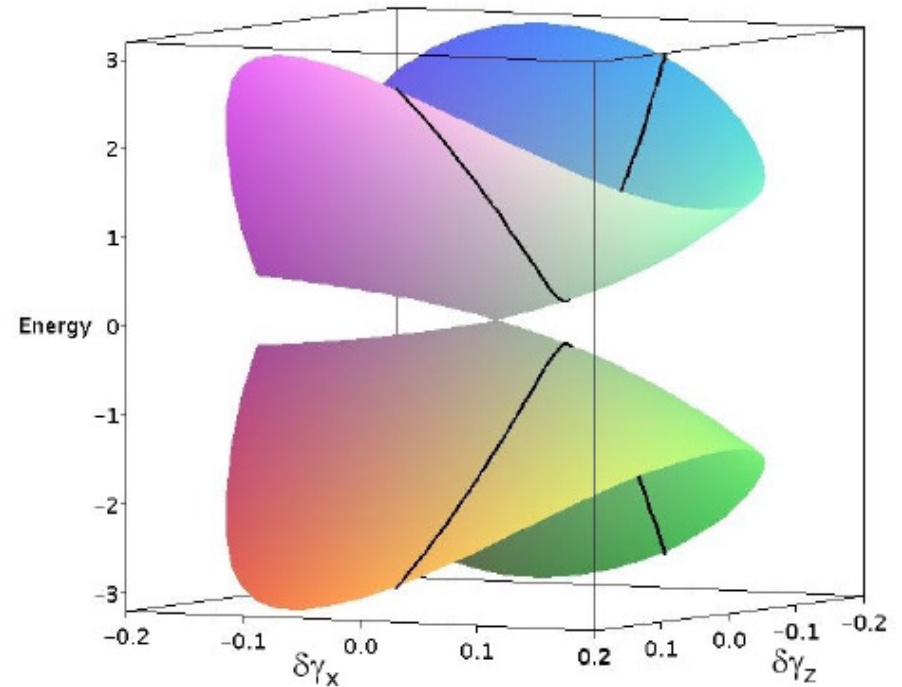
$$E_s[\gamma] = \text{Tr}(\hat{h}\hat{\gamma})$$

$$= \sum_j f_j \epsilon_j$$

$$\gamma_{j\sigma k\nu} = \langle \Psi_0 | c_{j\sigma}^\dagger c_{k\nu} | \Psi_0 \rangle$$

$$A = \frac{1}{2}(f_a - f_b)$$

$$A - A_0 = 0.03$$



Equations of motion

$$i\partial_t \gamma(x_1, x'_1; t) = (\hat{h}_0(x_1, t) - \hat{h}_0(x'_1, t))\gamma(x_1, x'_1; t) + 2\int dx_2 (v_c(x_1, x_2) - v_c(x'_1, x_2))\Gamma(x_1, x_2, x'_1, x_2; t)$$

$$i\partial_t |\phi_k\rangle = (\hat{t} + \hat{v}_{eff})|\phi_k\rangle$$

$$i\partial_t f_k = \langle \phi_k | \hat{w} | \phi_k \rangle$$

$$w(x, x') = 2\int dy (v_c(x, y) - v_c(x', y))\Gamma(x, y, x', y; t)$$

Müller functional

$$V_{ee} = \frac{1}{2} \sum \iint dr dr' \left[f_j f_k \frac{\phi_j^*(r)\phi_k^*(r')\phi_j(r)\phi_k(r')}{|r-r'|} - \sqrt{f_j f_k} \frac{\phi_j^*(r)\phi_k^*(r')\phi_k(r)\phi_j(r')}{|r-r'|} \right]$$

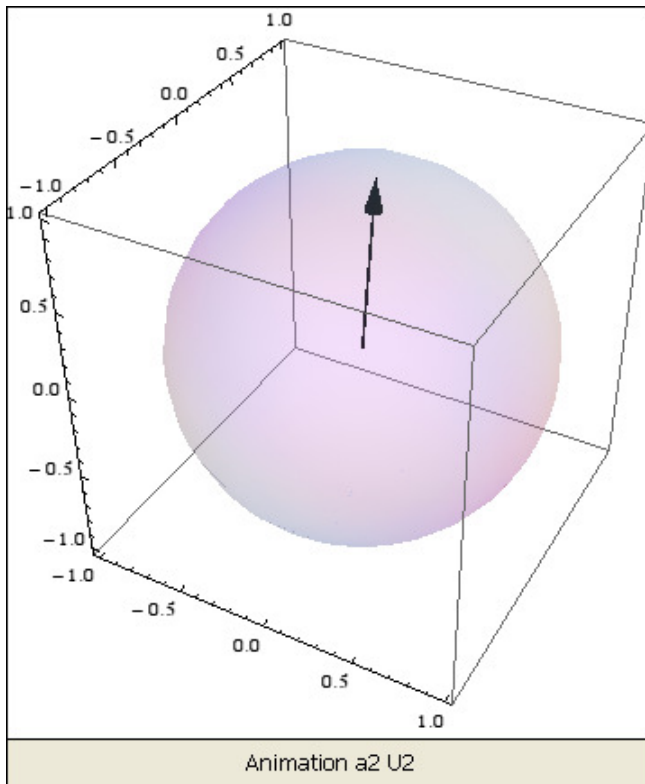
$$\text{for } \hat{\Gamma}_{ijkl} = F_{ijij} \delta_{ik} \delta_{jl} + G_{ijji} \delta_{il} \delta_{jk}$$

$$i\partial_t f_k = \langle \phi_k | \hat{w} | \phi_k \rangle = 0$$

Linear time dependence

$$V_3 = \alpha t$$

$$\dot{\vec{\gamma}} = \vec{V} \times \vec{\gamma} + \vec{W} \quad \vec{V} = (-2b, 0, V_3(t)) \quad \vec{W}(t) = W(\varphi(t), \theta(t), |\gamma(t)|)$$



$$\alpha = 2, U = 2$$

